

# COASTAL MOBILITY & LIVABILITY STUDY

City of Encinitas  
Planning and Building Department  
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CREATING A VISION FOR MOBILITY CONNECTIONS  
AND QUALITY OF LIFE IMPROVEMENTS  
ALONG THE COASTAL CORRIDOR



## What is the Coastal Mobility and Livability Study?

The study will examine:

- How people get around – for example, existing and future options for people of all ages and abilities to safely and conveniently travel. This includes pedestrians, cyclists, motorists, transit riders, etc.
- What types of changes are needed – for example, what type of improvements or changes would help make connections safer and more convenient.
- How can the corridor be more livable – for example, how to quiet train noise and enhance community character.

## Your Voice Counts!

We need your input to create a vision for the corridor. What improvements do you want to see? What are the community design characteristics that you want to preserve or introduce? Join us in October to describe them so City Council can understand your views in creating a vision for the corridor and improve the City's active transportation network. With your input, we will return in early 2017 with a draft vision.

## PLEASE JOIN US AT A WORKSHOP IN YOUR COMMUNITY!

### Leucadia:

Paul Ecke Central Elementary  
185 Union Street  
Wednesday, October 5, 6-8 p.m.

### Cardiff:

Cardiff Elementary  
1888 Montgomery Avenue  
Thursday, October 6, 6-8 p.m.

### Old Encinitas:

Encinitas Library  
540 Cornish Drive  
Saturday, October 8, 3-5 p.m.

### Olivenhain:

Olivenhain Town Hall  
423 Rancho Santa Fe Road  
Saturday, October 15, 3-5 p.m.

### New Encinitas:

Flora Vista Elementary  
1690 Wandering Road  
Monday, October 17, 6-8 p.m.

All workshops are the same.  
You may also participate  
using PlaceSpeak, the  
City's new online public  
participation tool.

[www.encinitasca.gov/cmls](http://www.encinitasca.gov/cmls)



## More about the CMLS?

There are three specialized studies that make up the CMLS:

1. Active Transportation Plan
2. Parking Study
3. Rail Corridor Vision Study



### PROJECT CONTACT

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## FREQUENTLY ASKED QUESTIONS...

### What is the Active Transportation Plan (ATP)?

The ATP will develop a citywide strategy or network to make it safer, more convenient, and more enjoyable for people to get around on a bike or walking.

### What is the Parking Study?

The Coastal Corridor Parking Study will examine how parking is currently being used (primarily on Coast Highway 101 and some nearby streets), identify near-term and long-term issues, and will ultimately develop a series of parking management strategies to make sure that parking is used efficiently in the future. This could mean more parking or alternatives to reduce the need to drive and park a car in the corridor.

### What is the Rail Corridor Vision Study (RCVS)?

The RCVS will provide a coordinated, comprehensive vision of improvements to the rail corridor. This study coordinates of a number of planned coastal rail corridor projects, such as double tracking, rail crossing improvements and implementation of the Coastal Rail Trail, among others. The RCVS may also identify new improvements within the coastal rail corridor, such as sheltered seating along trails and reducing train horn noise, among others.

### Why is your input important?

A goal of the CMLS is to make it easier, safer, and more comfortable for people to get around Encinitas, along with improving quality of life. Public input will help us develop solutions that make a real difference in Encinitas. The CMLS will ultimately provide a coordinated vision for community-supported mobility and livability improvements. Examples of possible mobility improvements include measures to help pedestrians, bicyclists, transit users and automobiles safely travel the corridor. Livability improvements could include reducing train noise and enhancing community design character.

For more information about how to participate in the CMLS process or for one of the three related studies, please visit: [www.encinitasca.gov/cmls](http://www.encinitasca.gov/cmls).

